

# Tools and Metrics for Vulnerability Assessment

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# A Scenario Inspired by EPRI/NESCOR Threat Scenario ET.16

A set of EVs/PVs/DERs is Exploited to Threaten Transformer or Substation

- **Vulnerability:** no protection of data integrity. Configuration commands may be corrupted

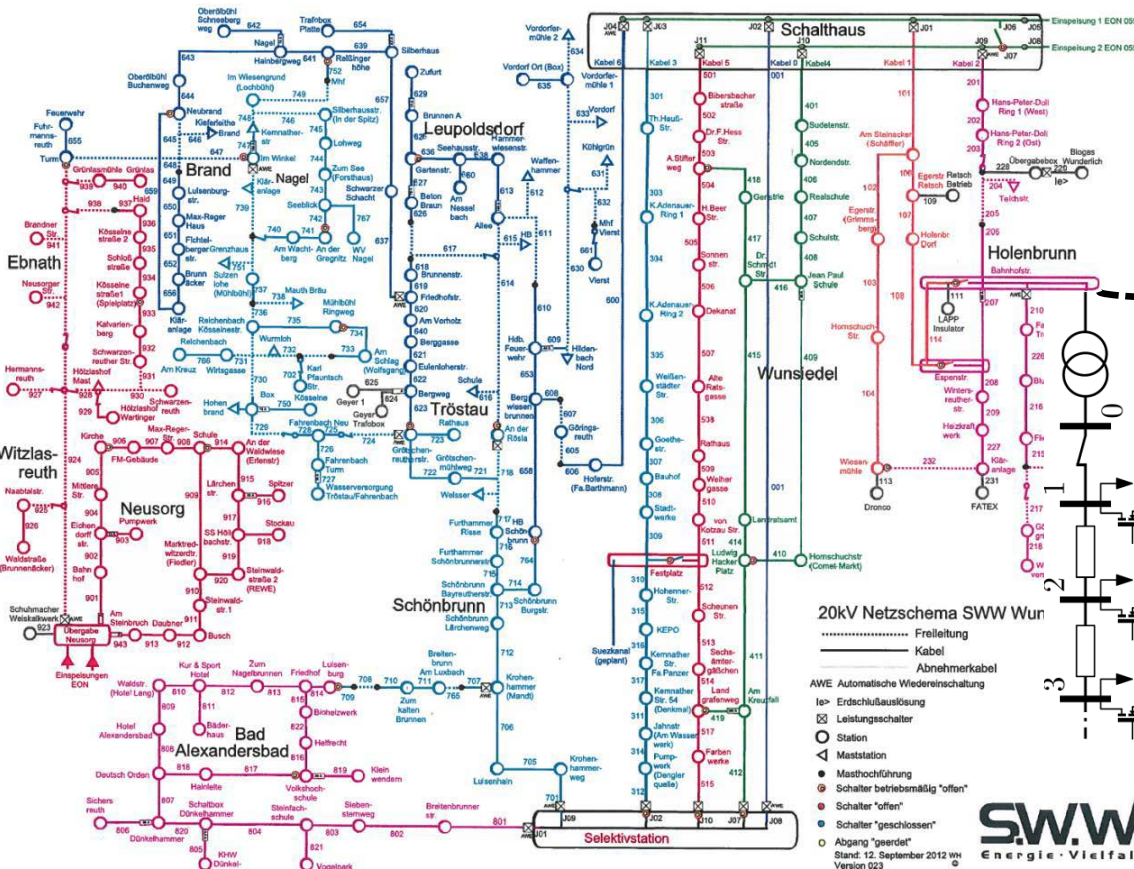


## Consequences:

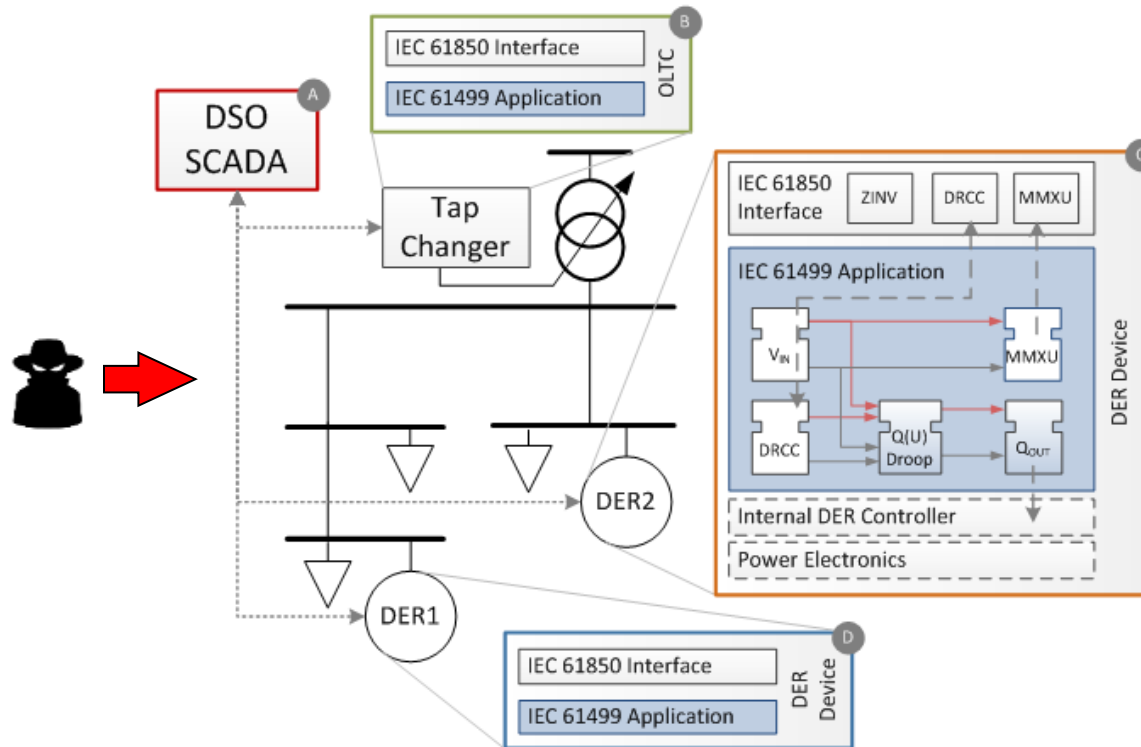
- Damage to transformer
- Cascading failure
- Economic losses

## Questions:

- What EVs/PVs/DERs are most vulnerable?
- Will cascading failure occur?
- How fast must the attack be detected?
- ...



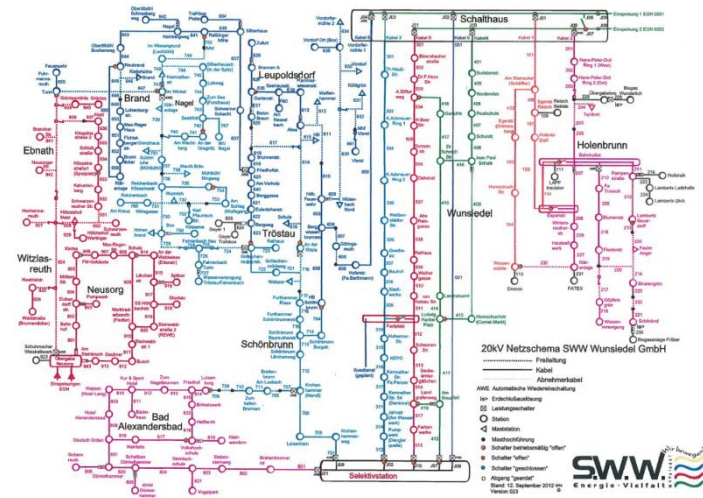
# IEC 61850 Standard: Distributed Control Approach for DER



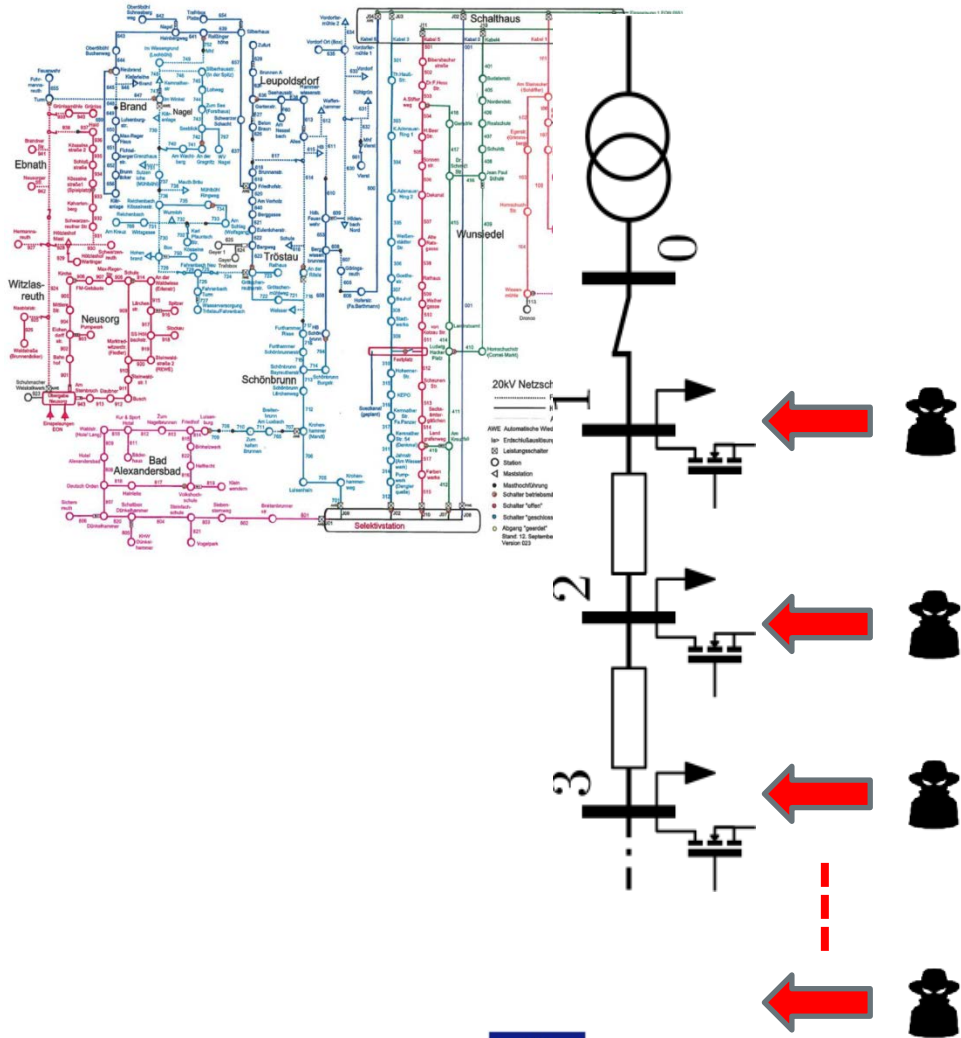
[Andrén *et al.*, IEEE Trans. Energy Conv., 2014]

# Goals and Challenges: Tools and Metrics

- Impossible to simulate every possible threat scenario
- Develop quantitative tools to localize most critical signals and equipment
  - Verification using detailed simulation
  - Allocation of protective resources
  - Design of resilient controllers
- Need simplified models to obtain tractable computational problems



# Example of Current Work

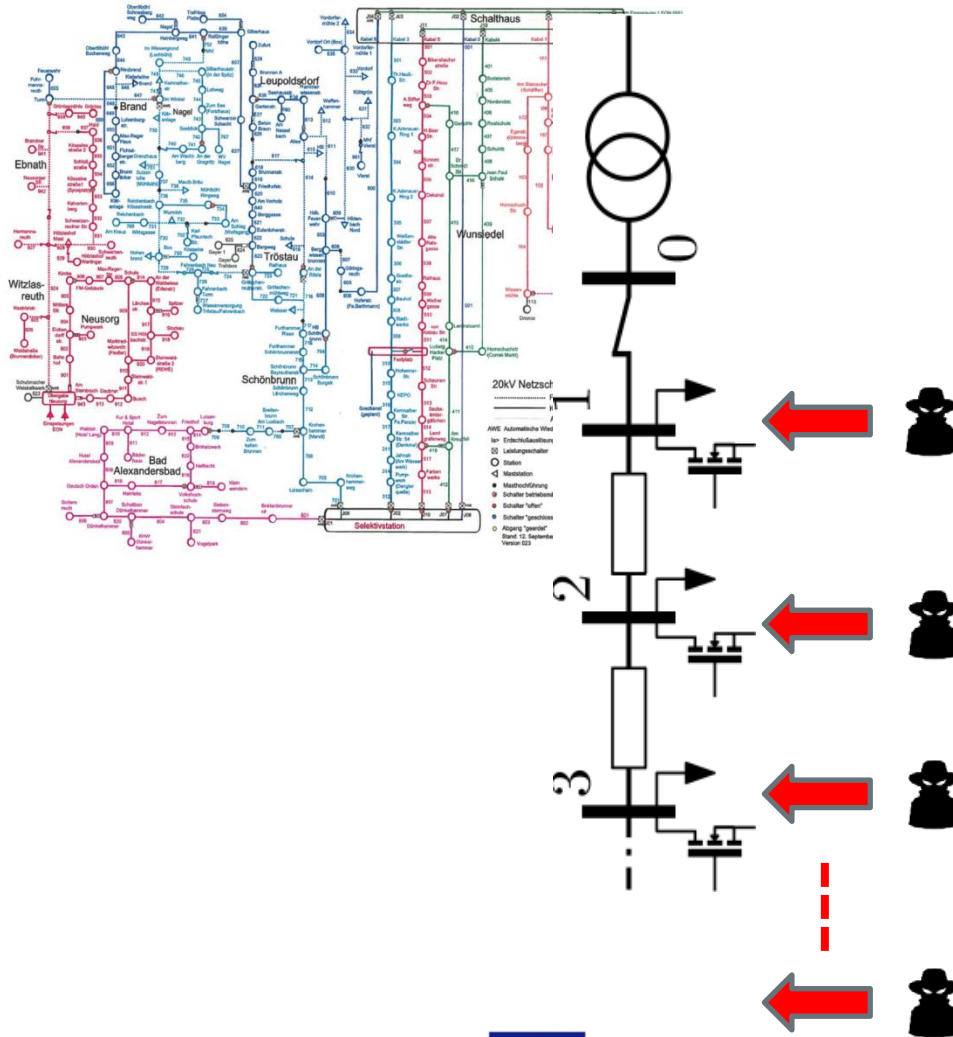


- PV controllers on a line attacked
- Possible damage
  - Fuses blown or components damaged
  - Forced islanding or load shedding
  - Degraded performance due to oscillation, or power quality
  - Forced switch in transformers and volt/VAR control, but no damage/instability
  - Economic losses





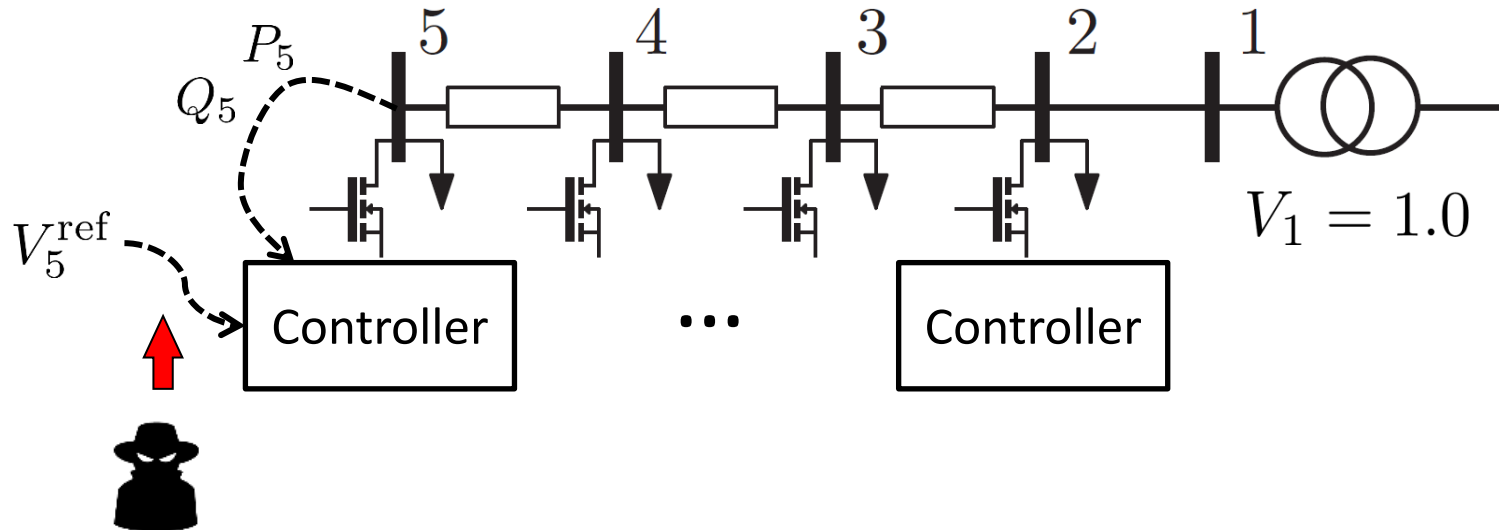
# Example of Current Work



- Scenarios
  - Coordinated (botnet) attack
  - Local attack
  
- Metric
  - Electrical impact vs. #attacked PV control signals



# A 5-Node System: Setpoint for Node 5 Attacked

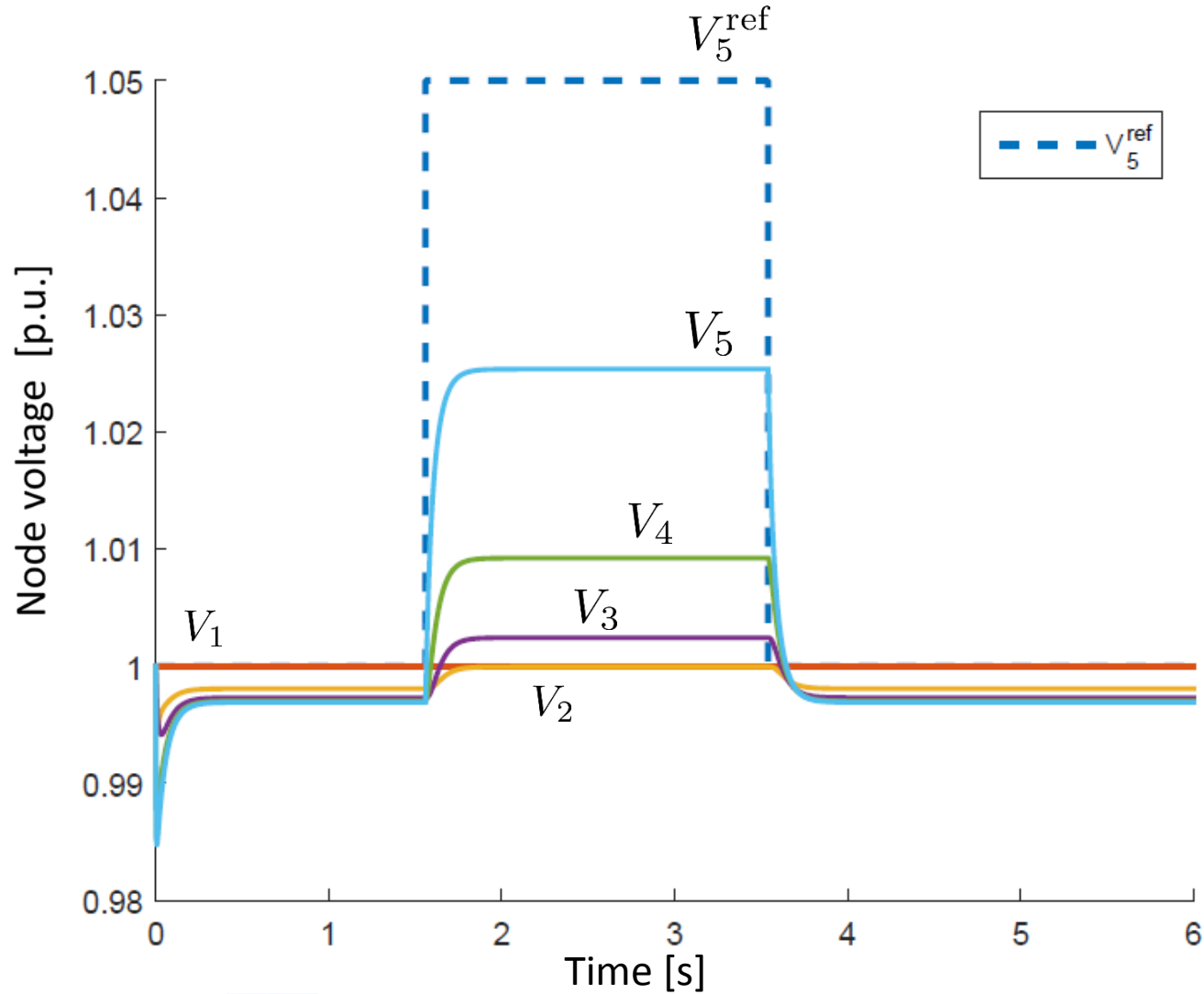


- PV inverter node dynamics ( $C_i$  control gains):

$$\tau_i \dot{V}_i(t) = -C_i V_i(t) [V_i(t) - V_i^{\text{ref}}(t)] - \tilde{Q}_i(t), \quad i = 2, 3, 4, 5$$

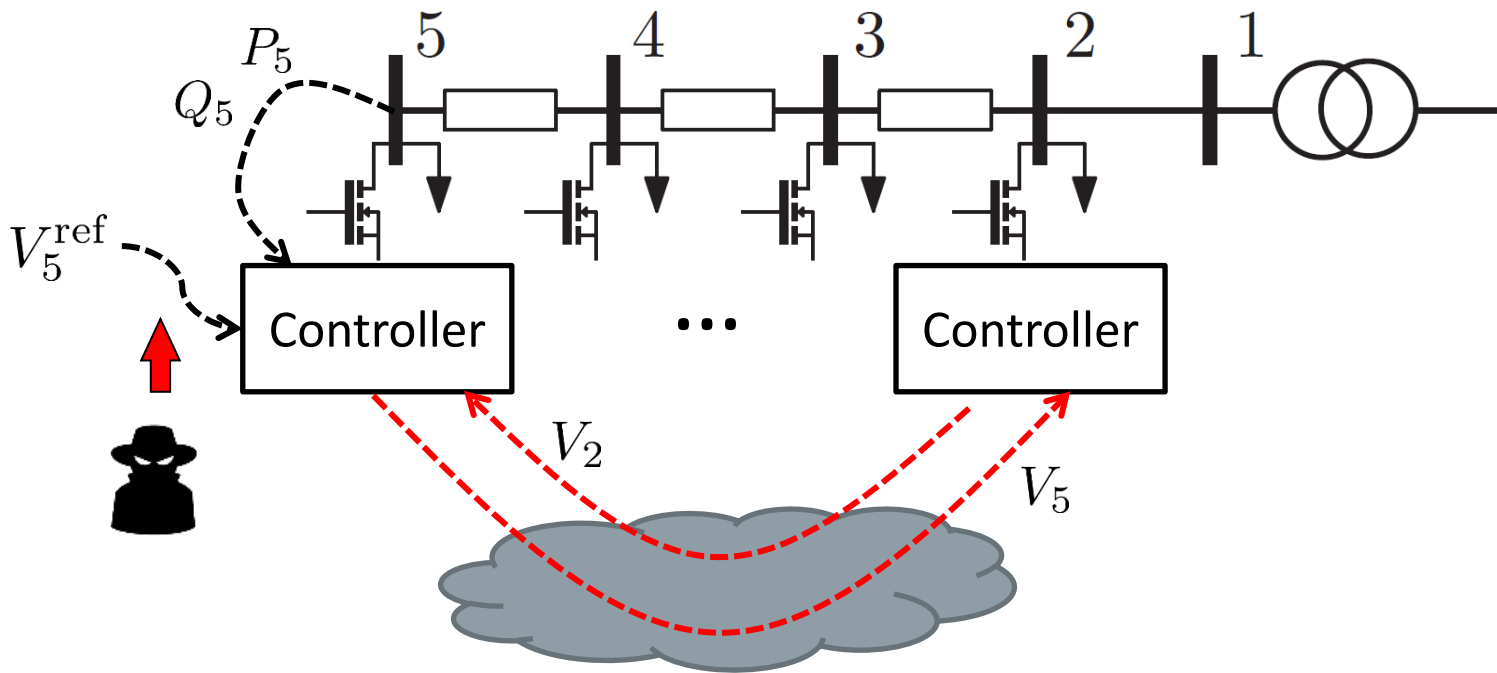
$$\tilde{Q}_i(t) = \frac{1}{1 + \rho^2} [Q_i(t) - \rho P_i(t)]$$

# Simulation Result

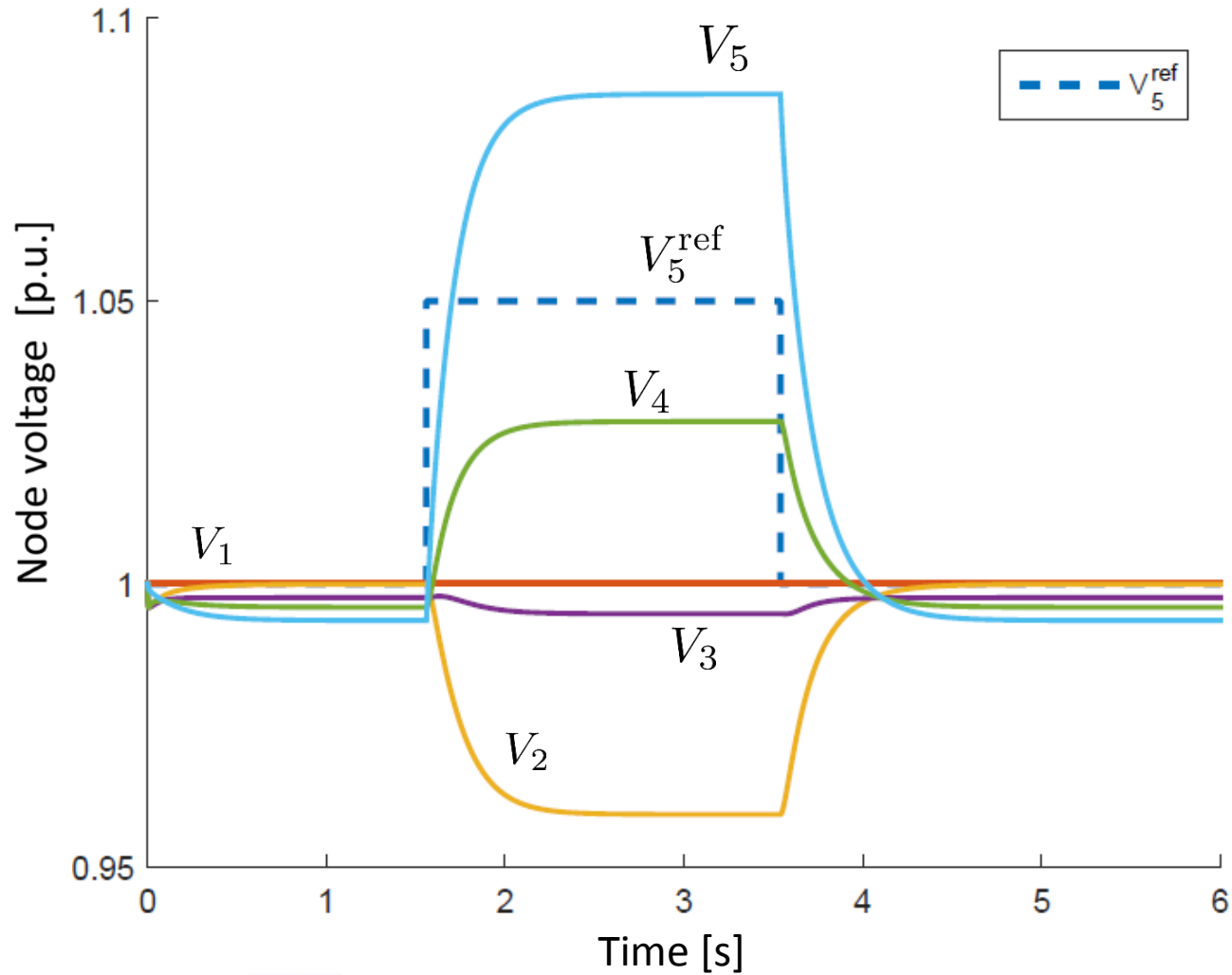




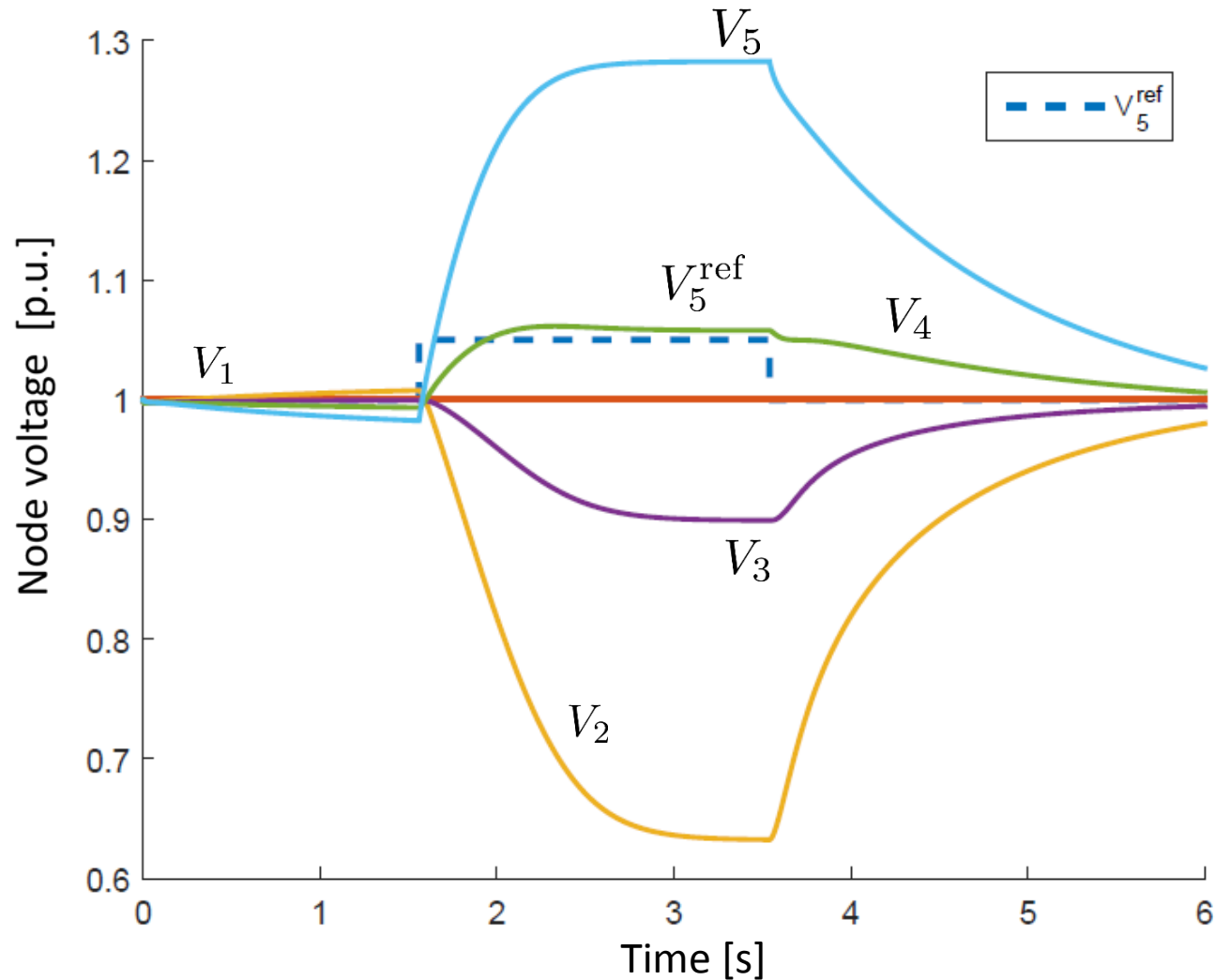
# A 5-Node System: Attacker Swaps Measurements for Node 2 and 5



# Simulation Result



# Simulation Result (50% Higher Control Gains $C_i$ )



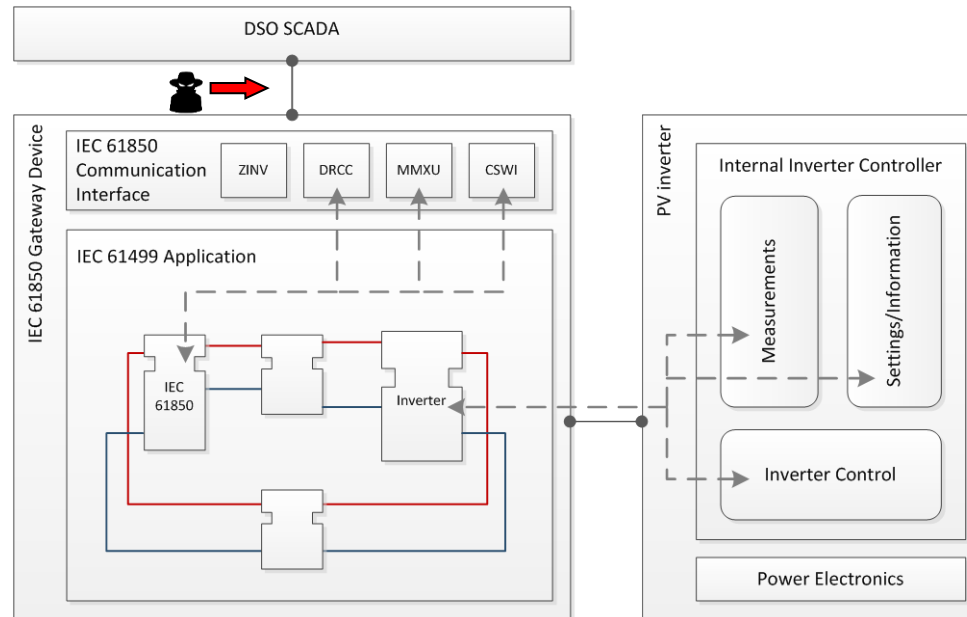
# Insights from Simulations

- Effects of attack against the reference decay with electrical distance
  
- But attacker may also swap measurements on the communication bus
  - Complete change of dynamical behavior: non-decaying perturbations, over- and undershoot, oscillations, ...
  - How to detect swaps?
  - Which swaps are dangerous?
  - How far can the misbehavior spread?
  - ...

# Summary and Discussion

- Combinatorial explosion of the number of possible attacks in a Smart Grid...
- Need for quantitative tools and metrics for vulnerability assessment and resilient control design
- Example: Local and coordinated attacks against PV nodes in a Smart Grid
- A simple simulation example

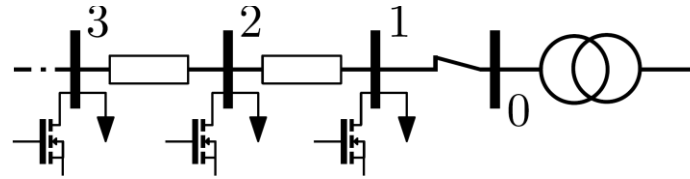
# Communication Protocol: IEC 61850



## ■ Search for weaknesses in

- IEC 61850-90-7 — Object Models for Photovoltaic, Storage and other DER inverters
- IEC 61850-7-420 — Communications systems for Distributed Energy Resources (DER) - Logical nodes

# Simple Model of PV Inverters and Controllers



- States
  - Voltage level:  $V_i$
  - Phase angle:  $\theta_i$
- Transmission Line  $Y_{ij} = G_{ij} + jB_{ij}$ 
  - Homogeneous line ratio:  $\rho = \frac{G_{ij}}{B_{ij}}$

- Power injections:
 
$$P_i = \sum_{j \in \mathcal{V}} V_i V_j (G_{ij} \cos(\theta_i - \theta_j) + B_{ij} \sin(\theta_i - \theta_j)),$$

$$Q_i = \sum_{j \in \mathcal{V}} V_i V_j (G_{ij} \sin(\theta_i - \theta_j) - B_{ij} \cos(\theta_i - \theta_j))$$

- Voltage droop controller:

$$\tau_i \dot{V}_i = -C_i V_i (V_i - V_i^{\text{ref}}) - \tilde{Q}_i$$

$$\tilde{Q}_i = \frac{1}{1 + \rho^2} (Q_i - \rho P_i)$$

